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From the point of view of a user this book



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covers all aspects of modern electrical drives. It is aimed at both users, who wish to understand, design, use, and maintain electrical drives, as well as specialists, technicians, engineers, and students, who wish to gain a comprehensive overview of electrical drives. Jens Weidauer and Richard Messer describe the principles of electrical drives, their design, and application, through to complex automation solutions. In the process, they introduce the entire spectrum of drive solutions available and their main applications. A special aspect is the combination of multiple drives to form a drive system, as well as the integration of drives into automation solutions. In simple and clear language, and supported with many diagrams, complex relationships are described and presented in an easy-to-understand way. The authors deliberately avoid a comprehensive mathematical treatment of their subject and instead focus on a coherent description of the active principles and relationships. As a result, the reader will be in a position to understand electrical drives as a whole and to solve drive-related problems in everyday professional life.

This volume includes extended and revised versions of a set of selected papers from the International Conference on Electric and Electronics (EEIC 2011) , held on June 20-22 , 2011, which is jointly organized by Nanchang University, Springer, and IEEE IAS

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Nanchang Chapter. The objective of EEIC 2011 Volume 3 is to provide a major interdisciplinary forum for the presentation of new approaches from Electrical Power Systems and Computers, to foster integration of the latest developments in scientific research. 133 related topic papers were selected into this volume. All the papers were reviewed by 2 program committee members and selected by the volume editor Prof. Xiaofeng Wan. We hope every participant can have a good opportunity to exchange their research ideas and results and to discuss the state of the art in the areas of the Electrical Power Systems and Computers.

This book provides a comprehensive introduction into the fundamental physics and basic technical principles of automatic control and drive technology. It pays particular attention to the design and dimensioning of electrical feed drives in automation technology. It helps engineers and technicians to put into practice the theoretical fundamentals of automatic control and drive technology for machines in the tool, glass and ceramics industries as well as in the woodworking and packaging industries. It also deals with the application of robots and other manipulators. The relationships between automatic control and mechanical engineering are described and explained, making the book also particularly useful for students of technical disciplines.

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This book presents the latest cutting-edge technology in high-power converters and medium voltage drives, and provides a complete analysis of various converter topologies, modulation techniques, practical drive configurations, and advanced control schemes. Supplemented with more than 250 illustrations, the author illustrates key concepts with simulations and experiments. Practical problems, along with accompanying solutions, are presented to help you tackle real-world issues.

CE Marking for Low Voltage Directive is the essential reference for all manufacturers/exporters of electronic products to the European Economic Area (EEA). In this one volume, you get the complete text of the Low-Voltage Directive, along with a step-by-step overview and explanation of the certification procedure. It presents everything you need to know about the requirements the Directive imposes on your electronic products. Specifically written for American manufacturers, it covers all the frequently asked questions about the Directive. Comprehensive and easy-to-understand text, practical examples and well-organized diagrams and drawings make this volume an

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important new resource on meeting the requirements for compliance and getting your products to market in the EEA.

SIMATIC is the worldwide established automation system for implementing industrial control systems for machines, manufacturing plants and industrial processes. Relevant open-loop and closed-loop control tasks are formulated in various programming languages with the programming software STEP 7. Now in its sixth edition, this book gives an introduction into the latest version of engineering software STEP 7 (basic version) . It describes elements and applications of text-oriented programming languages statement list (STL) and structured control language (SCL) for use with both SIMATIC S7-300 and SIMATIC S7-400, including the new applications with PROFINET and for communication over industrial Ethernet. It is aimed at all users of SIMATIC S7 controllers. First-time users are introduced to the field of programmable controllers, while advanced users learn about specific applications of the SIMATIC S7 automation system. All programming examples found in the book - and even a few extra examples - are available at the download area of the publisher's website.

This book introduces non-identifier-based adaptive control (with and without internal model) and its application to the current, speed and position control of mechatronic

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systems such as electrical synchronous machines, wind turbine systems, industrial servo systems, and rigid-link, revolute-joint robots. In mechatronics, there is often only rough knowledge of the system. Due to parameter uncertainties, nonlinearities and unknown disturbances, model-based control strategies can reach their performance or stability limits without iterative controller design and performance evaluation, or system identification and parameter estimation. The non-identifier-based adaptive control presented is an alternative that neither identifies the system nor estimates its parameters but ensures stability. The adaptive controllers are easy to implement, compensate for disturbances and are inherently robust to parameter uncertainties and nonlinearities. For controller implementation only structural system knowledge (like relative degree, input-to-state stable zero dynamics and known sign of the high-frequency gain) is required. Moreover, the presented controllers guarantee reference tracking with prescribed asymptotic or transient accuracy, i.e. the tracking error eventually tends to or for all time evolves within an a priori specified region. The book presents the theory, modeling and application in a general but detailed and self-contained manner, making it easy to read and understand, particularly for newcomers to the topics covered

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A step-by-step guide to building an electric motorcycle from the ground up. Written by alternative fuel expert Carl Vogel, this hands-on guide gives you the latest technical information and easy-to-follow instructions for building a two-wheeled electric vehicle--from a streamlined scooter to a full-sized motorcycle. Build Your Own Electric Motorcycle puts you in hog heaven when it comes to hitting the road on a reliable, economical, and environmentally friendly bike. Inside, you'll find complete details on every component, including motor, batteries, and frame. The book covers electric motorcycles currently on the market and explains how to convert an existing vehicle. Pictures, diagrams, charts, and graphs illustrate each step along the way. Whether you want to get around town on a sleek ride or cruise the super slab on a tricked-out chopper, this is the book for you. Build Your Own Electric Motorcycle covers:

- Energy savings and environmental benefits
- Rake, trail, and fork angle
- Frame and design
- Batteries and chargers
- DC and AC motor types
- Motor controllers
- Accessories and converters
- Electrical system and wiring
- Conversion process
- Safety, maintenance, and troubleshooting

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