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## Riemannian Contact

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Differential geometry is a mathematical discipline that uses the techniques of differential calculus, integral calculus, linear algebra and multilinear algebra to study problems in geometry. The theory of plane and space curves and surfaces in the three-dimensional Euclidean space formed the basis for development of differential geometry during the 18th century and the 19th century.

Differential geometry - Wikipedia

The first three chapters are really a prelude to the core of the book, which is an exposition of the differential geometry of a symmetric, positive-definite 2-tensor (Riemannian geometry), a nondegenerate one-

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form (contact geometry), and a closed, non-degenerate two-form (symplectic geometry).

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First, symplectic spaces are defined (just as Euclidean geometry dealt with nondegenerate positive definite forms, here we deal with symplectic forms that are skew-symmetric); then, the basic concepts are dealt with,

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including a discussion of  
diffeomorphisms of, and certain  
geometric sets in, symplectic spaces.

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Differential geometry arguably offers the smoothest transition from the standard university mathematics sequence of the first four semesters in calculus, linear algebra, and differential equations to the higher levels of abstraction and proof encountered at the upper division by mathematics majors. Today it is possible to describe differential geometry as "the study of structures on the tangent space," and this text develops this point of view. This book, unlike other introductory texts in differential geometry, develops the architecture necessary to introduce symplectic and contact geometry alongside its Riemannian cousin. The

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The main goal of this book is to bring the undergraduate student who already has a solid foundation in the standard mathematics curriculum into contact with the beauty of higher mathematics. In particular, the presentation here emphasizes the consequences of a definition and the careful use of examples and constructions in order to explore those consequences.

Elementary Differential Geometry presents the main results in the differential geometry of curves and surfaces suitable for a first course on the subject. Prerequisites are kept to an absolute minimum – nothing beyond first courses in linear algebra and multivariable calculus – and the

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most direct and straightforward approach is used throughout. New features of this revised and expanded second edition include: a chapter on non-Euclidean geometry, a subject that is of great importance in the history of mathematics and crucial in many modern developments. The main results can be reached easily and quickly by making use of the results and techniques developed earlier in the book. Coverage of topics such as: parallel transport and its applications; map colouring; holonomy and Gaussian curvature. Around 200 additional exercises, and a full solutions manual for instructors, available via [www.springer.com](http://www.springer.com) ul

In the past decade there has been a significant change in the freshman/sophomore mathematics curriculum

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as taught at many, if not most, of our colleges. This has been brought about by the introduction of linear algebra into the curriculum at the sophomore level. The advantages of using linear algebra both in the teaching of differential equations and in the teaching of multivariate calculus are by now widely recognized. Several textbooks adopting this point of view are now available and have been widely adopted. Students completing the sophomore year now have a fair preliminary understanding of spaces of many dimensions. It should be apparent that courses on the junior level should draw upon and reinforce the concepts and skills learned during the previous year. Unfortunately, in differential geometry at least, this is usually not the case. Textbooks directed to students at this level

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generally restrict attention to 2-dimensional surfaces in 3-space rather than to surfaces of arbitrary dimension. Although most of the recent books do use linear algebra, it is only the algebra of  $\mathbb{R}^3$ . The student's preliminary understanding of higher dimensions is not cultivated.

This book is a translation of an authoritative introductory text based on a lecture series delivered by the renowned differential geometer, Professor S S Chern in Beijing University in 1980. The original Chinese text, authored by Professor Chern and Professor Wei-Huan Chen, was a unique contribution to the mathematics literature, combining simplicity and economy of approach with depth of contents. The present translation is aimed at a wide

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audience, including (but not limited to) advanced undergraduate and graduate students in mathematics, as well as physicists interested in the diverse applications of differential geometry to physics. In addition to a thorough treatment of the fundamentals of manifold theory, exterior algebra, the exterior calculus, connections on fiber bundles, Riemannian geometry, Lie groups and moving frames, and complex manifolds (with a succinct introduction to the theory of Chern classes), and an appendix on the relationship between differential geometry and theoretical physics, this book includes a new chapter on Finsler geometry and a new appendix on the history and recent developments of differential geometry, the latter prepared

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especially for this edition by Professor Chern to bring the text into perspectives.

This textbook explores advanced topics in differential geometry, chosen for their particular relevance to modern geometry processing. Analytic and algebraic perspectives augment core topics, with the authors taking care to motivate each new concept. Whether working toward theoretical or applied questions, readers will appreciate this accessible exploration of the mathematical concepts behind many modern applications. Beginning with an in-depth study of tensors and differential forms, the authors go on to explore a selection of topics that showcase these tools. An analytic theme unites the early chapters,

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which cover distributions, integration on manifolds and Lie groups, spherical harmonics, and operators on Riemannian manifolds. An exploration of bundles follows, from definitions to connections and curvature in vector bundles, culminating in a glimpse of Pontrjagin and Chern classes. The final chapter on Clifford algebras and Clifford groups draws the book to an algebraic conclusion, which can be seen as a generalized viewpoint of the quaternions. Differential Geometry and Lie Groups: A Second Course captures the mathematical theory needed for advanced study in differential geometry with a view to furthering geometry processing capabilities. Suited to classroom use or independent study, the text will appeal to students and professionals

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alike. A first course in differential geometry is assumed; the authors' companion volume *Differential Geometry and Lie Groups: A Computational Perspective* provides the ideal preparation.

This book offers an introduction to differential geometry for the non-specialist. It includes most of the required material from multivariable calculus, linear algebra, and basic analysis. An intuitive approach and a minimum of prerequisites make it a valuable companion for students of mathematics and physics. The main focus is on manifolds in Euclidean space and the metric properties they inherit from it. Among the topics discussed are curvature and how it affects the shape of space, and the generalization of the fundamental

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theorem of calculus known as Stokes' theorem.

This book is divided into fourteen chapters, with 18 appendices as introduction to prerequisite topological and algebraic knowledge, etc. The first seven chapters focus on local analysis. This part can be used as a fundamental textbook for graduate students of theoretical physics. Chapters 8–10 discuss geometry on fibre bundles, which facilitates further reference for researchers. The last four chapters deal with the Atiyah-Singer index theorem, its generalization and its application, quantum anomaly, cohomology field theory and noncommutative geometry, giving the reader a glimpse of the frontier of current research in theoretical physics.

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## Riemannian Contact

This book provides an introduction to topology, differential topology, and differential geometry. It is based on manuscripts refined through use in a variety of lecture courses. The first chapter covers elementary results and concepts from point-set topology. An exception is the Jordan Curve Theorem, which is proved for polygonal paths and is intended to give students a first glimpse into the nature of deeper topological problems. The second chapter of the book introduces manifolds and Lie groups, and examines a wide assortment of examples. Further discussion explores tangent bundles, vector bundles, differentials, vector fields, and Lie brackets of vector fields. This discussion is deepened and expanded in the third chapter,

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which introduces the de Rham cohomology and the oriented integral and gives proofs of the Brouwer Fixed-Point Theorem, the Jordan-Brouwer Separation Theorem, and Stokes's integral formula. The fourth and final chapter is devoted to the fundamentals of differential geometry and traces the development of ideas from curves to submanifolds of Euclidean spaces. Along the way, the book discusses connections and curvature--the central concepts of differential geometry. The discussion culminates with the Gauß equations and the version of Gauß's theorema egregium for submanifolds of arbitrary dimension and codimension. This book is primarily aimed at advanced undergraduates in mathematics and physics and is intended as the

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template for a one- or two-semester  
bachelor's course.

Pressley assumes the reader knows the main results of multivariate calculus and concentrates on the theory of the study of surfaces. Used for courses on surface geometry, it includes interesting and in-depth examples and goes into the subject in great detail and vigour. The book will cover three-dimensional Euclidean space only, and takes the whole book to cover the material and treat it as a subject in its own right.

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